# Statistical Enhancement (Variance Reduction) for Monte Carlo Simulation

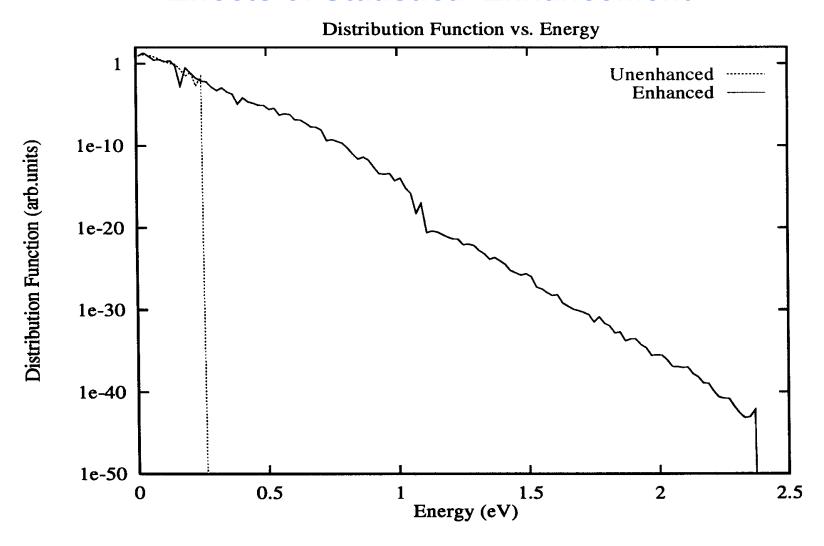
Umberto Ravaioli

Beckman Institute and
Department of Electrical and Computer Engineering
University of Illinois at Urbana-Champaign
Urbana, IL 61801, USA

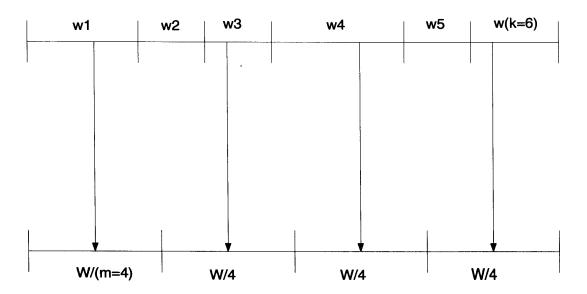
# **Monte Carlo simulation is noisy**

- Some of the noise is "real" and reflects the true nature of the conduction processes
- Some noise may be "numerical", due to the difficulty in having a large enough sample to collect needed statistics.
- Statistical enhancement is applied to remove particles where they are "oversampled" (real space or momentum space) and add particles where they are "undersampled"; or different weights are assigned to particles, so that rarely populated regions may have many particles with small weight, and highly populated regions may have few particle with large weight.
- Typical application is the resolution of high energy tails ofthe carrier distribution.

# **Effects of Statistical Enhancement**



## Multi-Comb Method

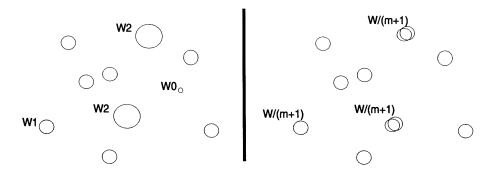


- k(=6) variable-weight particles are combed into m(=4) identical-weight particles with weight W/m(=4), where  $W = \sum_{i=1}^{k(=6)} w_i$ .
- The target number of particles per bin, m, is chosen in this study as the total number of particles divided by the number of occupied bins.
- All allocated particle memory is used throughout the simulation.
- Following a Multi-Comb, all particles in a phase-space bin have the same weight, W/m.

### DAMOCLES Method

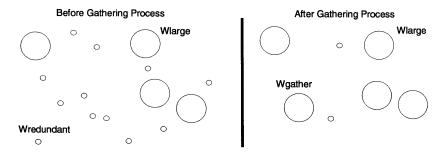
#### Before DAMOCLES Method

#### After DAMOCLES Method



- If a bin is unoccupied, the weight of the bin,  $w_b$ , is set to zero.
- If a bin is occupied but  $w_b$  is zero,  $w_b$  is set to the average weight of particles in the bin.
- If  $w_i < w_b$ , the  $w_i$ -weight particle is retained with probability  $\frac{w_i}{w_b}$  as a  $w_b$ -weight particle and is removed with probability  $1 \frac{w_i}{w_b}$ .
- If  $w_i > w_b$ , the  $w_i$ -weight particle is replaced with  $\zeta = int(\frac{w_i}{w_b})$   $w_b$ -weight particles with probability  $1 + \zeta \frac{w_i}{w_b}$ , or  $\zeta + 1$   $w_b$ -weight particles with probability  $\frac{w_i}{w_b} \zeta$ .
- The target number of particles per bin, m, is again chosen as the total number of particles divided by the number of occupied bins.
- If the number of particles in a bin falls outside  $\pm 20\%$  of the target number, particles are split or rouletted to change to approximately the target number.
- Following a DAMOCLES enhancement, all particles in a phase-space bin have the same weight.

### Adaptive Gather Method



- Particles (over all bins) are identified as "redundant" if they are smaller in weight than a larger particle in the same bin by the ratio relthre (=0.05 in this study).
- Using the set of redundant particles, groups of up to n (=10 in this study) may be gathered (grouped together as a single particle) if their weights differ by no more than ratio (=2 in this study).
- The target number of particles per bin is determined by the method (rather than chosen by the user) as 80% of the total number of particles over the number of occupied bins.
- In bins with occupation lower than target number, particles are split to match the target number.
- 80% of all particles are evenly distributed across all occupied bins and 20% of all particles are left in bins of the largest population.
- The gathering process allows the method to use all allocated particle memory throughout the simulation.
- Following an Adaptive Gather, all particles in a phase-space bin do not necessarily have the same weight.

# Test Runs for comparison of the techniques

Bulk simulation for undoped silicon, with 30,000 particles

Electric field 300 kV/cm

50 energy bins of width 0.1 eV from 0 to 5 eV

**Enhancement called every 1fs of simulation** 

Results were averages of 50 independent simulations of 3000 fs

Error performance analysis was done for steady-state, ignoring the initial 500 fs of the simulation.

